

Comprehensive Examination  
Quantitative Methods

The exams consists of three part. You are required to answer all the questions in all the parts.  
Good luck!

# Part I - 203A

1. The probability density of the random variable  $Y$  conditional on the random variable  $X = x$  is known to be of the form

$$f_{Y|X=x}(y) = \begin{cases} \lambda(x) e^{-\lambda(x)y} & \text{if } y > 0 \\ 0 & \text{otherwise} \end{cases}$$

where  $\lambda(x)$  is a function whose values are known to be nonnegative and bounded but it is otherwise unknown.

- (a) Suppose that  $X$  is known to have a binomial distribution with unknown parameters  $(n, p)$ . That is

$$\Pr(X = x) = \binom{n}{x} p^x (1-p)^{n-x} \quad x = 0, \dots, n$$

Determine what can be identified from the distribution of  $(Y, X)$ . Justify your answer.

- (b) Suppose that  $X$  is continuously distributed on the interval  $[1, 2]$  and it is known that for some positive, monotone increasing, and bounded, but otherwise unknown, function  $m(x)$  and for some positive but otherwise unknown parameter  $\alpha$

$$\lambda(x) = \alpha + m(x)$$

Determine what can be identified from the distribution of  $(Y, X)$ . Justify your answer. If a function or parameter is not identified, provide additional conditions under which it is identified and justify your answer.

- (c) Suppose now that

$$Z = \frac{1}{E[Y|X=x]} - \eta$$

where  $\eta$  is a random variable distributed independently of  $X$  with an unknown strictly increasing distribution function  $F_\eta$ , and that  $Y$  and  $\eta$  are not observed. Suppose that  $X$  is continuously distributed with support  $R$  and that the only objects that are observed are the density of  $X$  and

$$\Pr(Z \geq 0|X = x)$$

for all  $x$  in the support of  $X$ . Determine what functions and parameters can be identified from these observed objects. If a function or parameter is not identified, provide additional conditions under which it is identified and justify your answer.

2. The random variable  $Y$  is determined by the values of random variables  $X, \beta$ , and  $\varepsilon$  according to the model

$$Y = \beta X + \varepsilon$$

where  $(X, \beta, \varepsilon)$  is distributed Normal with mean  $(\mu_X, \mu_\beta, \mu_\varepsilon)$  and variance-covariance matrix

$$\Sigma = \begin{bmatrix} \sigma_{XX} & \sigma_{X\beta} & \sigma_{X\varepsilon} \\ \sigma_{X\beta} & \sigma_{\beta\beta} & \sigma_{\beta\varepsilon} \\ \sigma_{X\varepsilon} & \sigma_{\beta\varepsilon} & \sigma_{\varepsilon\varepsilon} \end{bmatrix}$$

- (a) Derive an expression in terms of the parameters, and as simple as possible, for the probability that  $Y \geq 0$  conditional on  $X = x$ .
- (b) Derive an expression in terms of the parameters, and as simple as possible, for the probability that  $Y \geq 0$ .
- (c) Obtain an expression for the mean of  $Y$ .
- (d) Obtain an expression for the variance of  $Y$ .
- (e) Suppose that  $\varepsilon$  is known to be distributed independently of the vector  $(X, \beta)$ . What can you say about the values of the mean and variance parameters of  $(X, \beta, \varepsilon)$ ? In this case, are  $\beta$  and  $\varepsilon$  independent conditional on  $X$ ? Explain.
- (f) Suppose that  $X$  and  $\beta$  are independently distributed. Let  $A$  denote the intersection of the following three events:  $(X \geq 1)$ ,  $(\beta \geq 1)$ , and  $(\beta X \leq 2)$ . Obtain an expression, in terms of the parameters, for the probability of  $A$ .

Note 1: You may use  $\phi(u)$  and  $\Phi(u)$  to denote, respectively, the density and cumulative distribution of a  $N(0, 1)$  random variable.

Note 2: You might find useful to recall that the Moment Generating Function of a random vector  $W$  distributed  $N(\mu, \Sigma)$  is  $M_W(t) = e^{t'\mu + (1/2)t'\Sigma t}$ .

## Part II - 203B

1. *No derivation is required for the two short questions below; your derivation will not be read anyway.*

(a) Suppose that

$$y_i = x_i\beta + \varepsilon_i$$

with  $(y_i, x_i)'$   $i = 1, \dots, n$  i.i.d., and  $E[x_i\varepsilon_i] = 0$ . We do NOT assume that  $E[\varepsilon_i^2|x_i]$  is constant. You are given the following data set with  $n = 3$ :

$$\begin{bmatrix} y_1 & x_1 \\ y_2 & x_2 \\ y_3 & x_3 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 3 & 1 \end{bmatrix}$$

Using the asymptotic normality of the OLS estimator as well as White's heteroscedasticity corrected estimator of the asymptotic variance, produce the 95% confidence interval of  $\beta$ . If your answer involves a square root, try to simplify as much as you can.

(b) We are given the following model:

$$q^d = \alpha_1 \cdot p + \alpha_2 \cdot y + \epsilon^d \quad (\text{Demand})$$

$$q^s = \beta_1 \cdot p + \beta_3 \cdot x + \epsilon^s \quad (\text{Supply})$$

$$q = q^d = q^s \quad (\text{Equilibrium})$$

We assume that the random vector  $(y, x)'$  is independent of the random vector  $(\epsilon^d, \epsilon^s)'$ . We also assume that  $E[\epsilon^d] = E[\epsilon^s] = 0$ . We have identified

$$E[p|y, x] = y - 2x$$

$$E[q|y, x] = 3y + 5x$$

What are numerical values of  $\beta_1$  and  $\alpha_1$ ?

2. *Your answer to this question will be evaluated based on the logical validity and coherence of your argument.*

Suppose that  $y_1, \dots, y_n$  are independent and identically distributed scalar random variables. Their common distribution is  $N(\theta, \sigma^2)$ . Using the Gauss-Markov Theorem stated below, derive the best linear unbiased estimator of  $\theta$ . (You do not need to prove the Gauss-Markov Theorem, but you should argue why this question satisfies the premises of the theorem. No other argument will be accepted.)

Gauss-Markov Theorem: If (i)  $y = X\beta + \varepsilon$ ; (ii)  $X$  is a nonstochastic matrix; (iii)  $X$  has a full column rank (Columns of  $X$  are linearly independent); (iv)  $E[\varepsilon] = 0$ ; (v)  $E[\varepsilon\varepsilon'] = \sigma^2 I_n$  for some positive number  $\sigma^2$ ; then OLS is BLUE.

3. *Your answer to this question will be evaluated based on the logical validity of your argument as well as the numerical accuracy.*

Suppose that

$$y_i = x_i\beta + \varepsilon_i$$

We observe  $(y_i, x_i, z_i)'$ ,  $i = 1, \dots, n$  i.i.d. We assume that (1) the random vector  $(x_i, z_i)'$  is independent of  $\varepsilon_i$ ; (2)  $E[\varepsilon_i] = 0$  and  $E[\varepsilon_i^2] = 1$ ; (3)  $E[x_i^2] = E[z_i^2] = 1$  and  $E[x_i z_i] = \frac{1}{2}$ . Derive the asymptotic distribution of

$$\begin{bmatrix} \sqrt{n} (\hat{\beta}_{OLS} - \beta) \\ \sqrt{n} (\hat{\beta}_{IV} - \beta) \end{bmatrix}$$

where

$$\hat{\beta}_{OLS} = \frac{\sum_{i=1}^n x_i y_i}{\sum_{i=1}^n x_i^2}, \quad \hat{\beta}_{IV} = \frac{\sum_{i=1}^n z_i y_i}{\sum_{i=1}^n z_i x_i}.$$

*Make sure that the asymptotic variance matrix consists of concrete numbers; if you stop with abstract formulae or your numbers are incorrect, your answer will be understood to be at best 30% complete.*

## Part III - 203C

1. Suppose that  $\{X_t\}_t$  is a second order auto-regressive process, i.e.

$$X_t = \phi_o X_{t-1} + \frac{1}{2} X_{t-2} + u_t,$$

where  $u_t \sim i.i.d.(0, \sigma_u^2)$ ,  $\sigma_u^2 > 0$  and  $u_t$  has finite 4-th moment. We have  $n$  observations on  $X_t$ :  $\{X_t\}_{t=1}^n$ .

- (a) Suppose  $|\phi_o| < \frac{1}{2}$ . Is  $\{X_t\}_t$  a weakly stationary process? Justify your answer.  
 (b) Suppose that  $\phi_o = 0$ . Derive the auto-covariance function of  $\{X_t\}_t$ .  
 (c) Suppose that  $\phi_o = 0$  and we know the value of  $\phi_o$ . Derive the long-run variance (LRV) of  $\{X_t\}_t$ . Provide a LRV estimator which is root-n consistent.  
 (d) Suppose that  $|\phi_o| < \frac{1}{2}$ . Show that  $\phi_o$  is identified by the following moment condition:

$$E \left[ (X_t - \phi_o X_{t-1} - \frac{1}{2} X_{t-2}) X_{t-1} \right] = 0. \quad (1)$$

- (e) Suppose that  $\phi_o = 0$  and we do not know the value of  $\phi_o$ . From the moment condition (1), we can construct the method of moment (MM) estimator of  $\phi_o$  as

$$\hat{\phi}_n = \frac{\sum_{t=3}^n (X_t - \frac{1}{2} X_{t-2}) X_{t-1}}{\sum_{t=2}^n X_t^2}.$$

Derive the asymptotic distribution of the above MM estimator.

- (f) Suppose that  $\phi_o = 0$  and we do not know the value of  $\phi_o$ . Show that  $\phi_o$  is identified by the moment conditions:

$$\begin{pmatrix} E [(X_t - \phi_o X_{t-1} - 2X_{t-2}) X_{t-1}] \\ E [(X_t - \phi_o X_{t-1} - 2X_{t-2}) X_{t-2}] \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}. \quad (2)$$

Find the asymptotic variance of the optimally weighted GMM estimator of  $\phi_o$  based on the moment conditions (2).

- (g) Compare the asymptotic variances of the optimally weighted GMM estimator and the MM estimator studied in (e) and explain your finding.

2. Consider the following model

$$X_t = \alpha_o t + u_t \text{ with } u_t = \sqrt{t}\varepsilon_t \quad (3)$$

where  $\varepsilon_t \sim i.i.d.(0, \sigma_\varepsilon^2)$  with  $\sigma_\varepsilon^2 > 0$ ,  $\varepsilon_t$  has finite 4-th moment, and  $\alpha_o$  and  $\sigma_\varepsilon^2$  are unknown parameters. We have  $n$  observations on  $X_t$ :  $\{X_t\}_{t=1}^n$ .

(a) Derive the asymptotic distribution of the LS estimator of  $\alpha_o$ :

$$\hat{\alpha}_n = \frac{\sum_{t=1}^n tX_t}{\sum_{t=1}^n t^2}. \quad (4)$$

(b) Construct a consistent estimator  $\hat{\sigma}_{\varepsilon,n}^2$  of  $\sigma_\varepsilon^2$ . Derive the asymptotic distribution of your estimator.

(c) Using the estimator  $\hat{\sigma}_{\varepsilon,n}^2$  of  $\sigma_\varepsilon^2$ , one can construct an estimator of the variance of  $u_t$  as  $\hat{\sigma}_{u_t,n}^2 = t\hat{\sigma}_{\varepsilon,n}^2$ . Consider the generalized LS (GLS) estimator of  $\alpha_o$ :

$$\hat{\alpha}_{gl,n} = \frac{\sum_{t=1}^n tX_t\hat{\sigma}_{u_t,n}^{-2}}{\sum_{t=1}^n t^2\hat{\sigma}_{u_t,n}^{-2}}. \quad (5)$$

Derive the asymptotic distribution of  $\hat{\alpha}_{gl,n}$ . Compare the asymptotic variances of the LS estimator and the GLS estimator and explain your findings.

## Some Useful Theorems and Lemmas

**Theorem 1 (Martingale Convergence Theorem)** Let  $\{(X_t, \mathcal{F}_t)\}_{t \in \mathbb{Z}_+}$  be a martingale in  $L^2$ . If  $\sup_t E[|X_t|^2] < \infty$ , then  $X_n \rightarrow X_\infty$  almost surely, where  $X_\infty$  is some element in  $L^2$ .

**Theorem 2 (Martingale CLT)** Let  $\{X_{t,n}, \mathcal{F}_{t,n}\}$  be a martingale difference array such that  $E[|X_{t,n}|^{2+\delta}] < \Delta < \infty$  for some  $\delta > 0$  and for all  $t$  and  $n$ . If  $\bar{\sigma}_n^2 > \delta_1 > 0$  for all  $n$  sufficiently large and  $\frac{1}{n} \sum_{t=1}^n X_{t,n}^2 - \bar{\sigma}_n^2 \rightarrow_p 0$ , then  $n^{\frac{1}{2}} \bar{X}_n / \bar{\sigma}_n \rightarrow_d N(0, 1)$ .

**Theorem 3 (LLN of Sample Variance)** Suppose that  $Z_t$  is i.i.d. with mean zero and  $E[Z_0^2] = \sigma_Z^2 < \infty$ . Let  $X_t = \sum_{k=0}^{\infty} \varphi_k Z_{t-k}$ , where  $\varphi_k$  is a sequence of real numbers with  $\sum_{k=0}^{\infty} k \varphi_k^2 < \infty$ . Then

$$\frac{1}{n} \sum_{t=1}^n X_t X_{t-h} \rightarrow_p \Gamma_X(h) = E[X_t X_{t-h}]. \quad (6)$$

**Theorem 4 (Donsker)** Let  $\{u_t\}$  be a sequence of random variables generated by  $u_t = \sum_{k=0}^{\infty} \varphi_k \varepsilon_{t-k} = \varphi(L)\varepsilon_t$ , where  $\{\varepsilon_t\} \sim iid(0, \sigma_\varepsilon^2)$  with finite fourth moment and  $\{\varphi_k\}$  is a sequence of constants with  $\sum_{k=0}^{\infty} k |\varphi_k| < \infty$ . Then  $B_{u,n}(\cdot) = n^{-\frac{1}{2}} \sum_{t=1}^{\lfloor n \cdot \rfloor} u_t \rightarrow_d \lambda B(\cdot)$ , where  $\lambda = \sigma_\varepsilon \varphi(1)$ .

**Theorem 5** For any natural number  $n$ , we have

$$\sum_{k=1}^n k = \frac{n(n+1)}{2} \quad \text{and} \quad \sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6}.$$